**MOBILE**

**PARTNER**

---

**Traceability and markings**

**MOBILE**

1. Body controls the manufacturer of the product.
2. Non-life body that carries out the type examination.
3. Approval of the Notified Body.
4. Body controls the manufacture of the product.

**PARTNER**

1. Traceability: diagramatic
2. Diameter
3. Individual number
4. Year of manufacture
5. Month of manufacture
6. Batch number
7. Individual identifier
8. Standards
9. Carefully read the instructions for use
10. Manufacturer address

---

**Field of application**

- **MOBILE**
  - 7 < Ø < 13 mm
- **PARTNER**
  - 7 < Ø < 11 mm

---

**Nomenclature**

**MOBILE**

1. 7 < Ø < 13 mm
2. 7 < Ø < 11 mm
3. UIAA

**PARTNER**

1. 7 < Ø < 11 mm

---

**Strenght**

5A. Working limit / Valeur d'utilisation maxi

- 5 kN

5B. Breaking load / Charge de rupture

- 15 kN

---

**Inspection, points to verify**

**PPE checking**

*Verification EP*

PETZL.COM

---

**Compatibilty**

**MOBILE**

1. Compatibility (partie texte)

**PARTNER**

1. Compatibility (partie texte)

---

**Technical Notice**

MOBILE / PARTNER

---

**3 year guarantee**
Efficiency

6A. Simple pulley system

with progress capture

6B. 2:1 hauling system

<table>
<thead>
<tr>
<th>Theoretical force</th>
<th>MOBILE</th>
<th>PARTNER</th>
</tr>
</thead>
<tbody>
<tr>
<td>P</td>
<td>F = P</td>
<td>F = P</td>
</tr>
<tr>
<td>F = 140 kg (MOBILE)</td>
<td>F = 110 kg (PARTNER)</td>
<td></td>
</tr>
<tr>
<td>F = 110 kg</td>
<td>Only PARTNER</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Theoretical force</th>
<th>MOBILE</th>
<th>PARTNER</th>
</tr>
</thead>
<tbody>
<tr>
<td>F = 0.5 P</td>
<td>F = 0.5 P</td>
<td></td>
</tr>
<tr>
<td>F = 0.58 P</td>
<td>F = 0.52 P</td>
<td></td>
</tr>
<tr>
<td>F = 0.66 P</td>
<td>F = 0.66 P</td>
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</table>

6C. 3:1 hauling system with progress capture

<table>
<thead>
<tr>
<th>Theoretical force</th>
<th>MOBILE</th>
<th>PARTNER</th>
</tr>
</thead>
<tbody>
<tr>
<td>P = 100 kg</td>
<td>F = 37 kg</td>
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</table>

<table>
<thead>
<tr>
<th>Theoretical force</th>
<th>MOBILE</th>
<th>PARTNER</th>
</tr>
</thead>
<tbody>
<tr>
<td>F = 0.33 P</td>
<td>F = 0.37 P</td>
<td></td>
</tr>
<tr>
<td>F = 0.57 P</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
7. Progress capture systems
Systemas anti-retour

8. Positioning and redirection
Positionnement et renvoi